

Closed loop demonstration with PA0160



IN1

Velocity mode 100 RPM in closed loop.

Torque can be adjusted with **Analogue Input**.

IN2

Velocity mode 100 RPM in open loop.

Torque can be adjusted with **Analogue Input**.

IN3

Torque search with 5 RPM. The motor changes direction when a load is applied.

IN4

Gear mode. The **Encoder Input** controls the motor. The **Analogue Input** determines the gear ratio.

Closed loop is enabled.

IN5

Motor runs back and forth with 100 RPM in closed loop.
